

H5U Series

High performance, compact, EtherCAT-enabled PLC

- · Compact footprint
- · PLCopen-compliant axis control
- · Simulation mode for offline debugging
- · Real-time fieldbus



H5U: high performance PLC

Programming

- · Supports function block and function for encapsulation, code reusability, and scalability
- · Efficient and easy-to-use ladder diagram programming, supporting graphic block instructions
- · User-defined variable programming with intuitive programming input assistant

Motion control

- · EtherCAT: 32-axis PTP motion control
- · PLCopen-compliant axis control
- · Local pulse and EtherCAT axis share the same motion control instructions
- · Axis group for lineal and circular interpolation
- · CAM tables functionality
- · 4 x high speed pulse output channels, to control stepper motors
- · Able to control servo drive via CANopen

Communications

- · Supports 72 EtherCAT slaves
- · 1 CAN interface: CANopen and CANlink master/slave
- · 1 RS485 interface: Modbus RTU master/slave
- · 1 Ethernet connection supports Modbus TCP and socket programming instructions

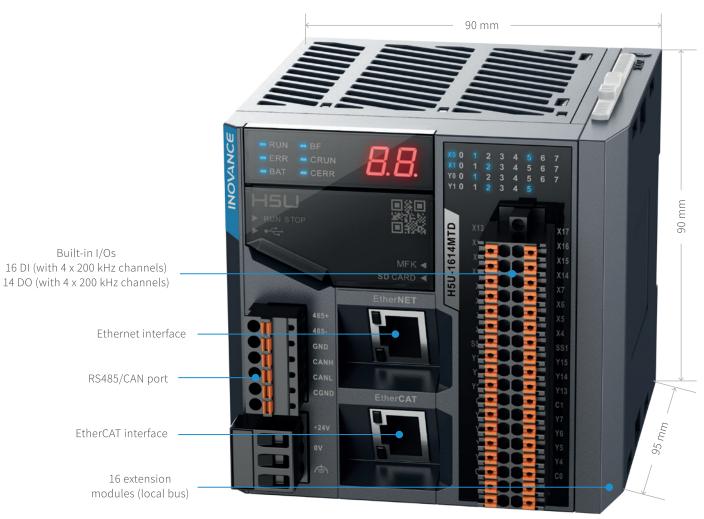
I/O configuration

- · Main unit with 16 inputs and 14 outputs, including high-speed I/Os
- · Supports up to 16 GL10 (AM600 series) local expansion modules
- · Remote GR10 I/O modules can be connected as EtherCAT slaves

Please note: refer to AM600 catalogue for more detail about our remote I/O modules

Commissioning

- · Simulation mode
 - PLC programs
 - Axis control
 - Local I/O
 - Serial and Ethernet comms
- · High-resolution trace tool
- · Program upload/download and firmware upgrade (only available with SD card)
- · Axis interface for easy test and monitoring



This image is illustrated in its actual size: W 90 mm x H 90 mm x D 95 mm

Model	H5U-1614MTD
Axis capacity	A total of 32 synchronised axes is possible. This can be a max. of 32 EtherCAT axes ¹ , or a combination that includes a max. of four pulse control axes
Communication specifications	EtherCAT: max. 72 EtherCAT slaves ² (including synchronised axes)
	Ethernet: Modbus TCP, socket programming
	CAN: supports CANlink and CANopen (only supports CANopen for axis control)
	RS485: Modbus RTU and free communication protocol
Program capacity	200 K-step user program
Data capacity	2 MB user-defined variables, of which 256 KB supports power failure retention
	Approx. 150 KB soft elements, of which 145 KB supports power failure retention
Programming language	LD, SFC, supporting function block/ function (LD)
High-speed I/Os	4 x 200 kHz high-speed inputs (2 encoder counting)
	8 x 200 kHz high-speed outputs (4-axes pulse output)
General I/Os	16 sink (NPN)/ source (PNP) inputs and 14 sink (NPN) outputs (including high-speed I/Os)
Module expansion	16 local modules, remote modules can be connected as EtherCAT slaves
Power input	+24 VDC
Other interfaces	USB SD card
Dimensions	L x W x H = 83 mm x 95 mm x 90 mm
Ordering code	01440087

¹Synchronised axes

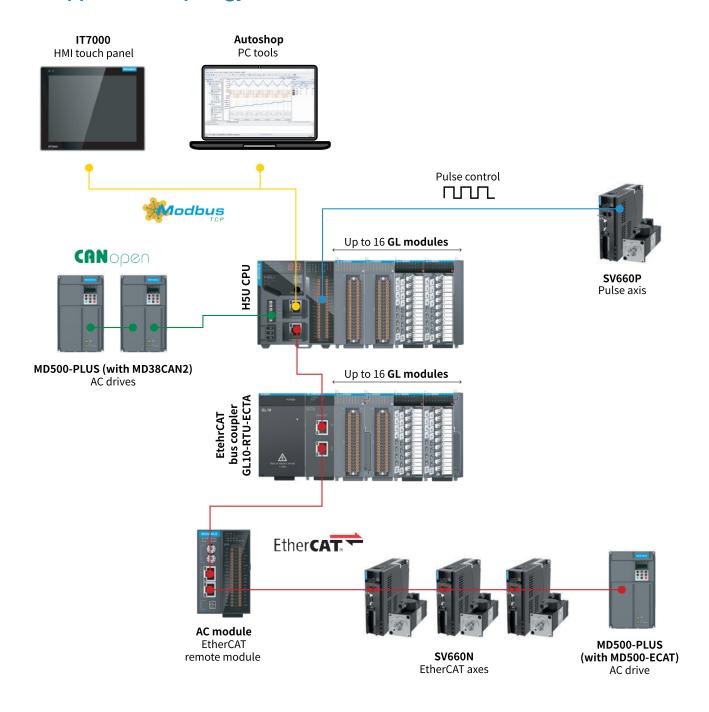
 $^{^{\}rm 2} Ether CAT$ slaves include I/Os and synchronised and non-synchronised axes







H5U - application topology





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